



Network Driver for LPC Devices User Guide

Version 1.30

For use with Network Driver for LPC Devices versions 3.02 and above

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1 System Overview

This chapter contains the fundamental information for this module.

The component sections are as follows:

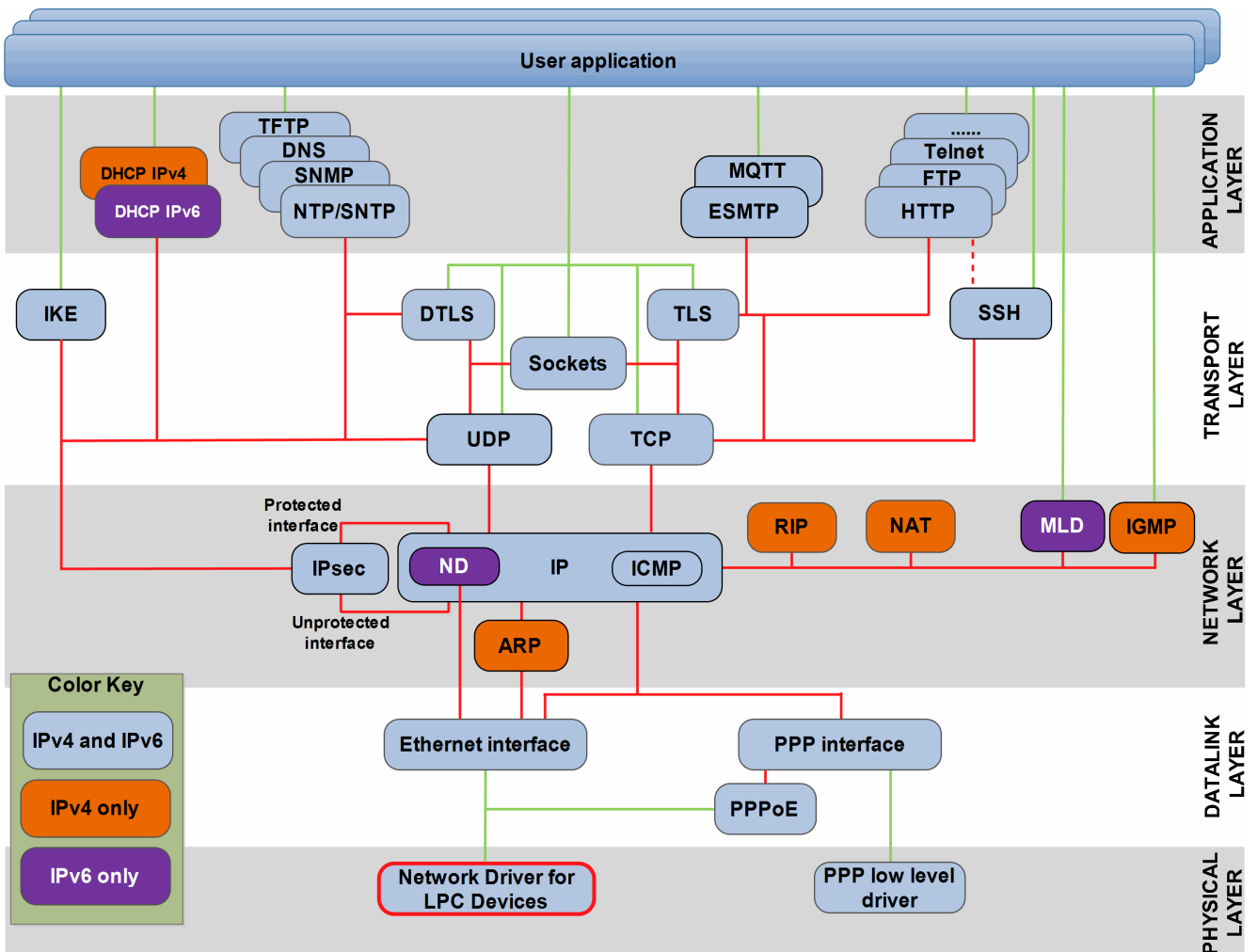
- [Introduction](#) – describes the main elements of the module. This section includes a diagram showing the position of the driver interface within HCC's TCP/IP stack.
- [Feature Check](#) – summarizes the main features of the module as bullet points.
- [Packages and Documents](#) – the *Packages* section lists the packages that you need in order to use this module. The *Documents* section lists the relevant user guides.
- [Change History](#) – lists the earlier versions of this manual, giving the software version that each manual describes.

Note: To download this manual as a PDF, see [Network Driver PDFs](#).

1.1 Introduction

This guide is for those who want to implement a network driver for Ethernet-capable LPC microcontrollers from NXP Semiconductors (now Qualcomm®).

The driver's location within HCC's TCP/IP stack is shown below. (In this diagram green lines show interfaces available to users of the TCP/IP stack, red lines show internal TCP/IP interfaces.)



Note: Although every attempt has been made to simplify the system's use, you need a good understanding of the requirements of the systems you are designing in order to obtain the maximum practical benefits. HCC Embedded offers hardware and firmware development consultancy to help you implement your system.

1.2 Feature Check

The main features of the network driver are the following:

- Conforms to the HCC Advanced Embedded Framework.
- Designed for integration with both RTOS and non-RTOS based systems.
- Conforms to the HCC Coding Standard, including full MISRA compliance.
- Fully compatible with the HCC Network Driver Interface specification.
- Supports LPC microcontrollers from NXP Semiconductors (now Qualcomm®).
- HCC provides fully tested reference drivers for this module.

1.3 Packages and Documents

Packages

The table below lists the packages which you need in order to use this module.

Package	Description
hcc_base_doc	This contains the two guides that will help you get started.
nw_drv_base	The network driver base package. This is the base system on which the LPC driver is built.
nw_drv_eth_lpc	The Network Driver for LPC Devices package.

Documents

For an overview of HCC's TCP/IP stack software, see [Product Information](#) on the main HCC website.

Readers should note the points in the [HCC Documentation Guidelines](#) on the HCC documentation website.

HCC Firmware Quick Start Guide

This document describes how to install packages provided by HCC in the target development environment. Also follow the *Quick Start Guide* when HCC provides package updates.

HCC Source Tree Guide

This document describes the HCC source tree. It gives an overview of the system to make clear the logic behind its organization.

HCC Network Driver User Guide

This document describes the network driver base system.

HCC Network Driver for LPC Devices User Guide

This is this document.

1.4 Change History

This section describes past changes to this manual.

- To download this manual or a PDF describing an [earlier software version](#), see [Network Driver PDFs](#).
- For the history of changes made to the package code itself, see [History: nw_drv_eth_lpc](#).

The current version of this manual is 1.30. The full list of versions is as follows:

Manual version	Date	Software version	Reason for change
1.30	2019-03-19	3.02	Improved <i>Source Files</i> , referencing PHY.
1.20	2018-10-30	3.02	Added PSP version files to <i>Source Files</i> . Improved <i>Configuration Options</i> .
1.10	2017-06-16	3.02	New <i>Change History</i> format.
1.00	2017-04-25	3.02	First online version.

2 Source File List

This section describes all the source code files included in the system. These files follow the HCC Embedded standard source tree system, described in the *HCC Source Tree Guide*. All references to file pathnames refer to locations within this standard source tree, not within the package you initially receive.

Note: Do not modify any files except the configuration files and PSP files.

2.1 API Header File

The file `src/api/api_ethdriver_lpc.h` should be included by any application using the system. This is the only file that should be included by an application using this module. It defines the `lpc_eth_drv_init` function.

2.2 Configuration Files

These files in the directory `src/config` contain all the configurable parameters of the system. Configure these as required. For details of these options, see [Configuration Options](#).

File	Description
<code>config_eth_phy_ksz8xxx.h</code>	KSZ8xxx PHY configuration.
<code>config_ethdriver_lpc.h</code>	LPC Ethernet driver configuration.

2.3 System Files

The following files are in the directory `src/driver/network/ethernet/lpc`. **These files should only be modified by HCC.**

File	Description
<code>eth_lpc.c</code>	LPC Ethernet driver code.
<code>eth_lpc_regs.h</code>	LPC header file.
<code>eth_phy_ksz8xxx.c</code>	KSZ8xxx PHY code.
<code>eth_phy_ksz8xxx_reg.h</code>	KSZ8xxx PHY header file.

There are files for specific devices in folders under `src`, for example `src/psp_lpc1768`.

2.4 Version Files

These files in the directory **src/version** contain the version numbers of the components of this module. The version number is checked by all modules that use a module to ensure system consistency over upgrades.

File	Description
ver_ethdriver_lpc.h	LPC driver version number.
ver_eth_phy_ksz8xxx.h	KSZ8xxx PHY version number.

2.5 Platform Support Package (PSP) Files

These files provide functions the core code needs to call, depending on the hardware. There is a folder named **psp_XXX** for each device type that HCC has implemented and also a generic set of files in **psp_template**.

The following general PSP implementation files are in the directory **src/psp**. These provide templates for you to produce your own PSP for other devices.

Note:

- You must modify these PSP implementations for your specific microcontroller and development board; see [PSP Porting](#) for details.
- In the package these files are offset to avoid overwriting an existing implementation. Copy them to the root **hcc** directory for use.

File	Description
include/psp_eth_mii.h	Media Independent Interface (MII) header file.
include/psp_eth_phy.h	PHY PSP header file.
target/eth/psp_eth_lpc.h	PSP functions header file.
target/eth/psp_eth_lpc.c	PSP functions source code (not in generic set).
target/eth/psp_eth_lpc_template.c	PSP functions source code (generic set only).
target/include/hcc_lpc2468_regs.h	Registers file (LPC2468 set only).

The PSP also has the following version files:

File	Description
ver_psp_eth_lpc.h	Source code version.
ver_psp_eth_mii.h	MII version.
ver_psp_eth_phy.h	PHY version.
ver_psp_proc_reg.h	Registers file version.

3 Configuration Options

Set the system configuration options in the two files in **src/config**, as described below. This section lists the available configuration options and their default values.

3.1 config_ethdriver_lpc.h

This file contains the following options:

ETHDRV_LPC_ISR_ID

The clock frequency. The default value is `ISR_ID (ETH_ISR, 0)`.

ETHDRV_LPC_ISR_PRIO

The Ethernet buffer size. The default value is 6.

ETHDRV_LPC_LINK_STATUS_POLLED

Keep this as the default of 1 to poll link status. Set this to 0 to handle this using interrupts.

ETHDRV_LPC_LINK_STATUS_POLL_INTERVAL

The poll interval in milliseconds, used if the previous option is enabled. The default value is 500.

ETHDRV_LPC_PHY_RMII

Keep this at the default of 1 if RMII mode is used. Otherwise set this to 0.

ETHDRV_RX_FEED_ENABLE

Keep this as the default of 1 to enable RX feed mode (meaning the IP stack provides RX buffers).

ETHDRV_LPC_RX_DESC

The number of receive descriptors. The default value is 4.

ETHDRV_LPC_TX_DESC

The number of transmit descriptors. The default value is 4.

ETHDRV_LPC_MAC_ADDRESS

The MAC address of the driver. The default value is { 0x00, 0xA2, 0x92, 0x00, 0x92, 0x33 }.

3.2 config_eth_phy_ksz8xxx.h

This file contains the following options:

ETH_PHY_LINK_ISR_ID

The Link ISR ID, defined in case it is used. The default value is xxx.

ETH_PHY_LINK_ISR_PRIO

The Link ISR priority, defined in case it is used . The default value is xxx.

ETH_PHY_DEV_ADDR

The physical device address. The default value is 1.

4 Application Programming Interface

This section describes the single Application Programming Interface (API) function and the error codes it may return.

4.1 lpc_eth_drv_init

Use this function to initialize the network driver.

Format

```
t_nwdriver_ret lpc_eth_drv_init (  
    uint32_t      param,  
    t_nwdriver * * const p_ethdriver )
```

Arguments

Parameter	Description	Type
param	The driver parameter.	uint32_t
p_ethdriver	Where to write the pointer to the driver.	t_nwdriver **

Return Values

Return value	Description
NWDRIVER_SUCCESS	Successful execution.
NWDRIVER_ERROR	Operation failed.

4.2 Error Codes

This table lists all the error codes that may be generated by the API calls:

Error code	Value	Meaning
NWDRIVER_SUCCESS	0	Execution successful.
NWDRIVER_ERROR	1	Operation failed.

5 Integration

This section describes all aspects of the network driver that require integration with your target project. This includes porting and configuration of external resources.

5.1 OS Abstraction Layer

The network driver uses the OS Abstraction Layer (OAL) that allows it to run seamlessly with a wide variety of RTOSes, or without an RTOS.

The network driver uses the following OAL components:

OAL Resource	Number Required
Tasks	0
Mutexes	0
Events	0
ISRs	1

5.2 Utilities

The code creates and uses a single timer in the **hcc_timer** module.

The **hcc_timer** module is included in your system when you install the base network driver module.

5.3 PSP Porting

The Platform Support Package (PSP) is designed to hold all platform-specific functionality, either because it relies on specific features of a target system, or because this provides the most efficient or flexible solution for the developer. For full details of its functions and macros, see the *HCC Base Platform Support Package User Guide*.

The module makes use of the following standard PSP function:

Function	Package	Element	Description
psp_memcpy()	psp_base	psp_string	Copies a block of memory. The result is a binary copy of the data.

The module makes use of the following functions that must be provided by the PSP. These are designed for you to port them easily to work with your hardware solution. The package includes samples in the **include/psp_eth_lpc_template.c** file.

Function	Description
psp_eth_lpc_init()	Initializes the hardware for the Ethernet driver.
psp_eth_lpc_start()	Starts the driver.
psp_eth_lpc_stop()	Stops the driver.
psp_eth_lpc_delete()	Deletes the driver, releasing associated resources.

These functions are described in the following sections.

psp_eth_lpc_init

This function is provided by the PSP to initialize the LPC Ethernet driver.

Format

```
t_nwdriver_ret psp_eth_lpc_init ( uint32_t module_id )
```

Arguments

Parameter	Description	Type
module_id	Where to store the buffer address.	uint32_t

Return Values

Return value	Description
NWDRIVER_SUCCESS	Successful execution.
NWDRIVER_ERROR	Operation failed.

psp_eth_lpc_start

This function is provided by the PSP to start the LPC Ethernet driver.

Format

```
t_nwdriver_ret psp_eth_lpc_start ( void )
```

Arguments

None.

Return Values

Return value	Description
NWDRIVER_SUCCESS	Successful execution.
NWDRIVER_ERROR	Operation failed.

psp_eth_lpc_stop

This function is provided by the PSP to stop the LPC Ethernet driver.

Format

```
t_nwdriver_ret psp_eth_lpc_stop ( void )
```

Arguments

None.

Return Values

Return value	Description
NWDRIVER_SUCCESS	Successful execution.
NWDRIVER_ERROR	Operation failed.

psp_eth_lpc_delete

This function is provided by the PSP to delete the LPC Ethernet driver, releasing the associated resources.

Format

```
t_nwdriver_ret psp_eth_lpc_delete ( void )
```

Arguments

None.

Return Values

Return value	Description
NWDRIVER_SUCCESS	Successful execution.
NWDRIVER_ERROR	Operation failed.